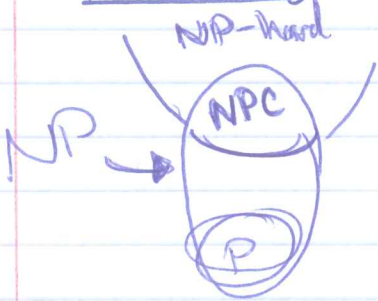


Ch 13: ILP.

# Satisfiability (and Complexity [Ch. 15].)



Reductions

~~NP~~ Def: P, NP, NP-complete

~~NP-complete P~~ Linear Programming is in P!

NP-complete Problem: 3-CNF-SAT

3 Conjunctive Normal Form:  $\bigwedge_{i=1}^m (\bigvee_j x_j)$

where each  $C_j(x) = \bigvee_{i=1}^3 x_i$   
clause.

Example:

$$\varphi(x_1, x_2, x_3, x_4) = (x_1 \vee x_2 \vee \bar{x}_4) \wedge (\bar{x}_2 \vee x_3 \vee x_4) \wedge (\bar{x}_1 \vee \bar{x}_3 \vee x_4)$$

$$\varphi(1, 0, 1, 0) = (1 \vee 0 \vee 1) \wedge (1 \vee 1 \vee 0) \wedge (0 \vee 0 \vee 0)$$

$$= 1 \wedge 1 \wedge 0 = 0$$

Satisfiability: Does there exist a vector  $x \in \{0, 1\}^n$  that satisfies  $\varphi(x) = 1$ .  
( $x$  satisfies  $\varphi$ ).

~~\* Linear~~

Integer Programming is NP-Hard

(Feasibility of ~~Bounded~~ ILP is NP-complete.)

\* Feas. in NP by selecting an integer point and solving the resulting LP for feasibility.

ILP is NP-Hard: Reduce ~~SAT~~ CNF-SAT to ILP.

Given  $\varphi(x_1, \dots, x_n)$ , make the following ILP:

Variables  $x_1, \dots, x_n \in \{0, 1\}$ .

For each clause,  $C_j$ , we make the following sum:

$$\sum_{i: x_i \in C_j} x_i + \sum_{i: \bar{x}_i \in C_j} (1 - x_i) = \text{B} |C_j|$$

~~If~~ A feasible point  $x$  exists  $\iff \varphi(x) = 1$ .

# Traveling Salesman on undirected vertices $\{0, \dots, n\}$

$$\min z = \sum_{\substack{i < j \\ i, j=0}}^n c_{ij} x_{ij}$$

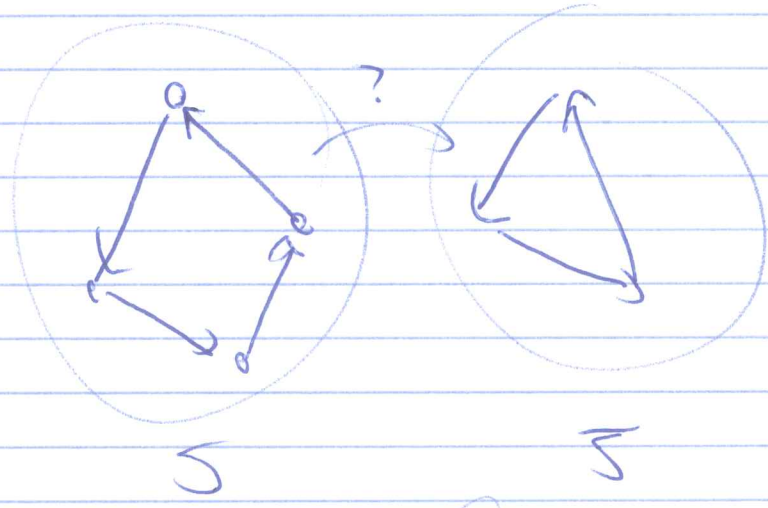
s.t.  $0 \leq x_{ij} \leq 1 \quad \forall i, j$   
 $x_{ij}$  integers } 0-1 LP

(a)  $\sum_{i=1}^n x_{ij} = 1 \quad \forall j$

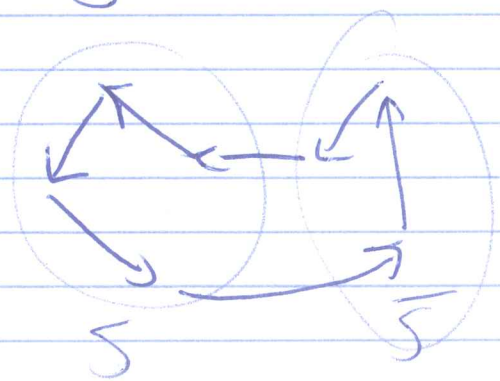
(b)  $\sum_{i=1}^n x_{ji} = 1 \quad \forall j$

(c)  $\sum_{\substack{i \in S \\ j \notin S}} x_{ij} \geq 1 \quad \forall S \subseteq [n], S \neq \emptyset$

$\uparrow$   
 $2^n - 2$  such sets!



(Iterative constraints?)



Better!

A.w. Tucker replaces (c) w/

$$(c'): u_i - u_j + nx_{ij} \leq n-1$$

important!  
0 is possible!  
 $\forall 1 \leq i \neq j \leq n$

where  $u_i \in \mathbb{R}$  for each  $i \in [n]$ . (MILP)

Prop: Constraints (a), (b) & (c') define the TSP.

Pf: First: Every Solution is a tour.

(By symmetry) We only need to show that every cycle includes 0.

Suppose  $i_1, \dots, i_k$  is a cycle.  $i_j \neq 0$ .

$$u_{i_j} - u_{i_{j+1}} + n \leq n-1 \quad j = 1, \dots, k-1$$

$$u_{i_k} - u_{i_1} + n \leq n-1.$$

Add all rows to find

$$kn \leq k(n-1). \quad \downarrow$$

Second: If  $T$  is a tour, there is a feasible point.

Let  $i_0, \dots, i_n$  be a tour w/  $i_0 = 0$ .

Let  $u_{i_j} = j$  for  $j \in \{0, \dots, n\}$ .

Now:  $u_{i_j} - u_{i_{j+1}} + n = j - (j+1) + n = n-1 \leq n-1$ .

~~Also  $u_{i_t} - u_{i_0} + n = (n-1) = 0$~~

But  $u_{i_n} - u_{i_0} + n$  is excluded! □

## Scheduling Problems

Multi-core Processors.

A list of computation requests come in, each has an approximate time to complete, some require others to be done before they start!

$J = \{J_1, \dots, J_n\} \leftarrow n$  jobs/tasks.

$J_i$  requires processing time  $\tau_i \geq 0$ . ( ~~$\tau_i \geq 0$~~ )

$J_i$  requires ~~res~~  $R_{j_i}$  of resource  $j$ .

There is  $B_j$  amount of resource  $j$  available at any given time.

The job  $J_i$  has a deadline  $d_i$ .

There are  $m$  processors,  $a_{i,j} \in \{0,1\}$   
indicates  $a_{i,j} = \begin{cases} 1 & \text{the } i^{\text{th}} \text{ job can run on the } j^{\text{th}} \text{ processor} \\ 0 & \text{otherwise} \end{cases}$

Precedence Relation:  $(J, A)$ , a digraph w/ no cycles.

$$T = \sum_{i=1}^n \tau_i$$

Formulation as MILP:

Let  $t, s_i \in \mathbb{R}_{\geq 0}$ , and  $p_{i,j} \in \{0,1\}$  be variables.

$s_i$  = starting time of job  $J_i$ .

$p_{i,j} = \mathbb{1}[J_i \text{ runs on processor } P_j]$

Optimize:  $\min t$  = time to completion.

Constraints:

①  $p_{i,j} \leq a_{i,j}$  (don't run on incompatible processors)

② (Let  $\delta_{i,k} = \mathbb{1}[s_i < s_k] \in \{0,1\}$ )

enforces property of  $\delta_{i,k}$   $\left\{ \begin{array}{l} s_k - s_i \leq \delta_{i,k} \cdot T \quad (\forall i \neq k) \\ \delta_{i,k} + \delta_{k,i} = 1 \quad (\text{exactly one has value 1}) \end{array} \right.$

If  $\delta_{i,k} = 1$   
and  $p_{i,j} = p_{k,j} = 1$ ,  
then  $s_i + \tau_i \leq s_k$ .

③ If  $(J_i, J_k) \in A$ , then  $J_k$  starts after  $J_i$ .

$\left. \begin{array}{l} \delta_{i,k} = 1 \\ s_i + \tau_i - s_k \leq 0 \end{array} \right\}$



#### ④ Resource Constraints.

At a given moment, a resource is not overused.

Let  $\varepsilon_{ijk} \geq 0$  be integers.

$$\varepsilon_{ijk} = \mathbb{1} [J_i \text{ is active when } J_k \text{ starts}]$$
$$\left\{ \begin{array}{l} \varepsilon_{ijk} \leq \delta_{ijk} \\ |t + (\varepsilon_{ijk} - 1)T \leq s_i + \tau_i - s_k \leq (\varepsilon_{ijk} + \delta_{ijk})T. \end{array} \right.$$

Resource constraints:

$$R_{j,k} + \sum_{i \neq k} (\varepsilon_{ijk} + \varepsilon_{k,i}) R_{j,i} \leq B_j$$

#### ⑤ Deadline Constraints

$$s_i + \tau_i \leq d_i$$

#### ⑥ Total Finishing Time

$$s_i + \tau_i \leq t.$$

|

# Strength of ILP

Disjunction:  $x \geq a$  <sup>costly</sup> or  $y \geq b$

Make new 0/1-variable  $\delta$

$$\left. \begin{array}{l} x \geq \delta \cdot a \\ y \geq (1-\delta) \cdot b \end{array} \right\} \text{ exactly one will be enforced.}$$

Implication If  $x \geq a$  then  $y \geq b$ .

Same as  $x \leq a$  or  $y \geq b$ .

(Strict inequalities are tricky.)

Discrete Variables?  $x \in S = \{s_1, \dots, s_k\} \subseteq \mathbb{R}$ .

$$\varepsilon_i = \mathbb{1} [x = s_i].$$

$$\sum_{i=1}^k \varepsilon_i = 1.$$

$$x = \sum_{i=1}^k s_i \varepsilon_i.$$